



YANSENSE® High-Precision Positioning System Management Software

Version 2.0



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1 Login

The landing page for a location system is the entry page for users to access and use the location system. This page provides functions such as entering accounts and passwords for user authentication and access to the system. This page can be customized to meet the specific needs of our customers.

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2 Overview

The global overview of the positioning system is a functional page that comprehensively displays and overviews the system status, equipment conditions, and key indicators. On the overview page, users can get a holistic view of the entire positioning system. This includes the health status of the system, device connectivity, key metrics, and real-time data. Users can visualize the overall status of the system and quickly obtain important information. This page can be customized to meet the specific needs of our customers.

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3 System settings

3.1 System settings

The System Settings tab of the positioning system is a functional module that provides management and viewing of some basic configurations and information of the system. This tab usually includes monitoring information such as system CPU usage, disk usage, and memory usage, as well as settings such as project configuration and system topology.

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3.2 Anchor management

Anchor equipment management is a key module in the positioning system, which is used to manage and monitor various information and parameters of anchor equipment. The module provides management and viewing functions for key information such as the serial number, IP address, MAC address, and XYZ coordinates of the anchor.

In anchor device management, users can view and record the serial number of the anchor, which is the number that uniquely identifies each anchor device. Serial number management helps to identify and distinguish different anchor devices, which is convenient for troubleshooting and maintenance management.

In addition, the anchor device management also provides the management function of the IP address and MAC address of the anchor. The IP address is the unique identifier of the anchor device in the network, while the MAC address is the physical address of the device. By managing and logging this address information, users can ensure the normal connection of the anchor equipment to the network, and perform network configuration and troubleshooting.

The anchor device management module also provides the management and viewing of the XYZ coordinates of the anchor. The XYZ coordinate represents the position coordinates of the anchor device in three-dimensional space, including abscissa, ordinate, and height. By managing the XYZ coordinates of the anchor, users can accurately understand the location information of each anchor device, which helps to plan and optimize the layout and coverage of the positioning system.

YANSENSE® High-Precision RTLS Management Software V2.0



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4 Real time position

The real-time positioning page is a functional module in the positioning system, specifically used to display and track real-time positioning trajectories based on UWB (ultra wideband) technology.

This page provides high-precision positioning capabilities through UWB technology and visualizes the real-time trajectory of moving objects. Users can view the position points of moving objects and their trajectory paths in time on the page.

The UWB real-time positioning trajectory page usually provides a map or plan view, which displays the position points and trajectory lines of the moving object. Users can zoom in, out, and pan the map view to view the movement path of the moving object in more detail.

In addition, when users select and import map data, the system will process and analyze it, and integrate it into the positioning system.









5 Tag management

The label management page is a functional module in the positioning system, used to manage and monitor various parameters and status information of positioning labels. This page provides real-time control and viewing functions for tags, allowing users to fully understand key information such as tag location, battery level, temperature, distress signal, and online status.

On the label management page, users can view the XY coordinates of the label, which are the positional coordinates in three-dimensional space, to understand the accurate position and motion trajectory of the label. This helps to monitor the position and movement of moving objects.

In addition to location information, the tag management page also provides monitoring of tag power and temperature. Users can view the remaining battery level of the label and the temperature of the environment in which the label is located. This information is crucial for evaluating the status and operational efficiency of equipment, as it enables timely detection of issues such as low battery or abnormal temperature.

The tag management page also provides monitoring of distress signals. If the positioning label encounters an emergency situation, users can receive relevant distress signals and take immediate action. This is of great significance for ensuring personal safety and emergency rescue.

In addition, the label management page also provides online status information for labels. Users can view the connection status of the tag, that is, whether the tag is online, active, or offline. This helps to ensure the normal operation of the device and promptly identify issues related to label connections.

The tag management page provides users with comprehensive management and monitoring capabilities for locating tags, helping them to real-time grasp key information such as tag location, power, temperature, distress signals, and online status. This enables users to better manage mobile objects, improve security, and optimize operational efficiency.





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6 Alarm record

The Alarm Record tab is a functional module in the positioning system used to record and view alarm events and related information that occur in the system. In the Alarm Record tab, users can view a list of alarm records, which contains detailed information about various alarm events that have occurred. Each alarm record typically includes the alarm time, alarm type, alarm location, and related additional information. Users can search and filter alarm records based on time range, alarm type, or other filtering criteria.

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7 Virtual Fence

The electronic fence option of the positioning system is a location-based technology used to set and manage virtual boundary ranges. Using UWB or GPS positioning technology, combined with software applications and devices, can help users monitor and control moving objects in specific areas.

Through the electronic fence option, users can create custom geographic areas and set corresponding alert conditions and trigger events. Once the monitored object (such as vehicles, personnel, or items) enters, leaves, or moves within the fence area, the system will be able to detect and trigger corresponding alarms, notifications, or automated operations in real-time.

The electronic fence option has a wide range of application scenarios. It can be used for fleet management to track and manage the driving range and entry and exit areas of vehicles. In logistics and supply chain management, electronic fences can help monitor the transportation process of goods, ensure that they proceed as planned, and provide real-time abnormal notifications. In addition, electronic fences can also be used for personal safety, such as child monitoring, pet tracking, and elderly care.

Through the electronic fence option of the positioning system, users can monitor and manage moving objects in specific areas in real-time, improving security, efficiency, and management capabilities, bringing many potential benefits to various industries.



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8 Historical trajectory

The historical trajectory option of the positioning system is a powerful technology used to record and replay the movement trajectory of moving objects in the past time. The historical trajectory option can collect and store the position information of moving objects for subsequent analysis and viewing.

Using the historical trajectory option, users can obtain detailed position records of specific moving objects over time. These records can include time, speed, direction, and information related to specific locations or events. Through visual interfaces or specific software tools, users can replay the motion trajectory of moving objects on the map and gain a deeper understanding of their behavior and path.

The historical trajectory option has a wide range of applications in various industries. In the field of logistics and transportation, it can help enterprises track the route and time of goods transportation, optimize transportation efficiency and arrangement. For the service industry and dispatch work, historical trajectories can provide employees' work paths and behavioral records to ensure the reliability and efficiency of task execution. In addition, historical trajectories also play a role in personal domains, such as motion tracking, travel records, and the safety of family members.

By using the historical trajectory option of the positioning system, users can obtain useful information about the past trajectory of moving objects, thereby enabling better analysis, planning, and decision-making. This technology provides rich data resources for various industries and provides users with deeper insights and management capabilities.





9 Trajectory export

The positioning system provides the function of exporting and saving trajectory data in CSV format, allowing users to save the trajectory data of moving objects in CSV file format to local or other systems. CSV (Comma Separated Values) is a common text file format that is easy to read and process.

By exporting the trajectory and saving it in CSV format, users can organize the position data of moving objects in chronological order and save it in a table format. Each row represents a point in time, containing timestamp and corresponding location information, such as XY coordinates, altitude, etc. CSV files can be opened using a text editor or spreadsheet software, facilitating subsequent analysis, processing, and visualization by users.

The advantage of saving trajectory data in CSV format lies in its versatility and flexibility. CSV files can be compatible with various data processing tools and systems, such as Excel, databases, or Geographic Information Systems (GIS). Users can customize the columns and data content of CSV files as needed to meet specific data analysis and application requirements.

By exporting and saving trajectory data in CSV format, users can save the trajectory data in the positioning system in a file format that is easy to process and share. This allows users to more flexibly utilize data for analysis, visualization, and integration into other applications to achieve deeper location analysis and decision support.



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标签管理	索引	标签序列号	人员名称	人员颜色	标签类型	X(m)	Y(m)	Z(m)	电量(%)	温度(°C)	气压值(Pa)	求救信号	创建时间
反警记录	185894	d1914900	d1914900		未指定	74.39	2.39						2023-07-17 16:53:42
电子围栏	185893	d1f05d15	d1f05d15		未指定	73.98	4.00						2023-07-17 16:53:41
历史轨迹	185892	d1e10c01	d1e10c01		未指定	73.45	2.42						2023-07-17 16:53:42
九迹寻出	185891	d183422b	d183422b		未指定	73.65	3.58						2023-07-17 16:53:41
	185890	d1f0dc84	d1f0dc84		未指定	74.06	2.42						2023-07-17 16:53:41
	185889	d1f01d92	d1f01d92		未指定	37.66	-6.94	0.00	64	36.00	0	安全	2023-07-17 16:53:42
	185888	d1e11d04	d1e11d04		未指定	38.10	-7.23	0.00	66	30.70	0	安全	2023-07-17 16:53:42
	185887	03b35216	03b35216		未指定	67.49	-6.57	0.00	64	36.50	0	安全	2023-07-17 16:53:42
	185886	d182db93	d182db93		未指定	19.24	-6.44	0.00	61	38.70	0	安全	2023-07-17 16:53:42
	185885	d1e5d503	d1e5d503		未指定	59.91	-6.58	0.00	58	38.70	0	安全	2023-07-17 16:53:42
	185884	d1f04100	d1f04100		未指定	51.05	-6.81	0.00	66	37.70	0	安全	2023-07-17 16:53:42
	185883	d182482e	d182482e		未指定	93.23	-7.57	0.00	48	35.20	0	安全	2023-07-17 16:53:42
	185882	d1914900	d1914900		未指定	74.43	2.11						2023-07-17 16:53:40
	185881	d1f05d15	d1f05d15		未指定	74.01	4.13						2023-07-17 16:53:40
	185880	d1e10c01	d1e10c01		未指定	73.44	2.43						2023-07-17 16:53:41
	185879	d183422b	d183422b		未指定	73.72	3.03						2023-07-17 16:53:40
	185878	d1f0dc84	d1f0dc84		未指定	73.87	3.16						2023-07-17 16:53:40
	185877	d1f01d92	d1f01d92		未指定	37.67	-6.98	0.00	64	36.00	0	安全	2023-07-17 16:53:41
0 build-23071711 ≡	185876	d1e11d04	d1e11d04		未指定	38.09	-7.31	0.00	66	30.70	0	安全	2023-07-17 16:53:41

扁总液	III / 轨迹导出												
肝迹 () 高精度尖时定 局急流 病範置 へ 系統配置 対意位 器管理 学部记 足 史知道 読号当	查询表格												
	人员名称输入	、汉字、字母或数字		创建的	时间 开始日期		- 结束日期		8				Q <u></u> 查询 (C)
站管理													
村定位	土 导出 🔵												G .
6管理	索引	标签序列号	人员名称	人员颜色	标签类型	X(m)	Y(m)	Z(m)	电量(%)	温度(°C)	气压值(Pa)	求救信号	创建时间
部记录	185894	d1914900	d1914900		未指定	74.39	2.39						2023-07-17 16:53:42
f围栏	185893	d1f05d15	d1f05d15		未指定	73.98	4.00						2023-07-17 16:53:41
电轨迹	185892	d1e10c01	d1e10c01		未描定	73.45	2.42						2023-07-17 16:53:42
29出	185891	d183422b	d183422b		未指定	73.65	3.58						2023-07-17 16:53:41
	185890	d1f0dc84	d1f0dc84		未指定	74.06	2.42						2023-07-17 16:53:41
	185889	d1f01d92	d1f01d92		未指定	37.66	-6.94	0.00	64	36.00	0	安全	2023-07-17 16:53:42
	185888	d1e11d04	d1e11d04		未指定	38.10	-7.23	0.00	66	30.70	0	安全	2023-07-17 16:53:42
	185887	03b35216	03b35216		未指定	67.49	-6.57	0.00	64	36.50	0	安全	2023-07-17 16:53:42
	185886	d182db93	d182db93		未指定	19.24	-6.44	0.00	61	38.70	0	安全	2023-07-17 16:53:42
	185885	d1e5d503	d1e5d503		未指定	59.91	-6.58	0.00	58	38.70	0	安全	2023-07-17 16:53:42
	185884	d1f04100	d1f04100		未指定	51.05	-6.81	0.00	66	37.70	0	安全	2023-07-17 16:53:42
	185883	d182482e	d182482e		未指定	93.23	-7.57	0.00	48	35.20	0	安全	2023-07-17 16:53:42
	185882	d1914900	d1914900		未指定	74.43	2.11						2023-07-17 16:53:40
	185881	d1f05d15	d1f05d15		未指定	74.01	4.13						2023-07-17 16:53:40
	185880	d1e10c01	d1e10c01		未指定	73.44	2.43						2023-07-17 16:53:41
	185879	d183422b	d183422b		未指定	73.72	3.03						2023-07-17 16:53:40
	185878	d1f0dc84	d1f0dc84		未指定	73.87	3.16						2023-07-17 16:53:40
	185877	d1f01d92	d1f01d92		未指定	37.67	-6.98	0.00	64	36.00	0	安全	2023-07-17 16:53:41





		E I	192.168.1.6	0:0000	rajecto	ryExpo	n												T 48	A*	中 ☆		@ 1	- 83	
1	研迹®高精度	实时过	主位系统																下载	巨轨迹 (1).xlsx			··· \$?	0) (a
4	周总宽	Β	ڻ ، چ	- =							历史	轨迹 (1) [受保	护的视图] - 6	icel (未经授权产	品)			登录		- 0	×				
5	(统设置	文件	开始	揻	、 页面	布局	公式 影	87 ¥	1月 1月11	報助	♀ 垂作说明独3	ŧ								5	đ Hà				
	系统配置	A1	Ŧ		× ~	f _x	索引														~				
	NORMUEL	1	 索引	1	B 創建日	时间	标金	C 各序列号		D 日称	E X(m)	F Y(m)	G Z(m)	H 电量(%)	I 温度(℃)	」 「三丁丁」 「二丁丁」」	K 求救信号	L 标签工作确认	X	N	0		Q 查询	¢	こ 重要
	基站管理	2					53:56 d1f0		d1f05d15		73.77	4.13													
		3					53:56 d1e1		d1e10c01		73.18	3.17									_				
3	时定位	4	186061 186060				53:56 d183		d183422b d1f0dc84		73.40 73.95	3.39												C	T:
		6	186059				53:56 d1f0		d1f01d92		37.67	-6.99	0.00	66	3 36.00	(FALSE	FALSE							
杤	签管理	7					3:56 d1e1		d1e11d04		38.06	-7.33	0.00		7 30.70		FALSE	FALSE					0178-0		
		8	186057				53:56 03b3		03b35216		67.51	-6.74	0.00		4 36.70	(FALSE	FALSE					创建的	10	
折	警记录	9	186056				53:56 d182		d182db93		19.21	-6.52	0.00		38.50		FALSE	FALSE				3	023-07-17	16-52-	42
-0		10	186055				53:56 d1e5		d1e5d503		59.88	-6.55	0.00		3 38.70		FALSE	FALSE				2	123-01-11	10.53%	re.
p‡	子围栏	11					53:56 d1f0		d1f04100		51.04	-6.89	0.00		3 37.70		FALSE	FALSE				2	023-07-17	16-52-	41
1	A PRIME	12	186053				53:56 d182		d182482e		93.22	-7.67	0.00	48	3 34. 50	(FALSE	FALSE				2	163-01-11	10.53%	
	10.00	13 14	186052 186051				53:54 d191 53:55 d1f0		d1914900 d1f05d15		74.21	2.10										2	023-07-17	16:52	42
D,	5史轨迹	19	186051				53:55 diru 53:54 diei		d1105d15 d1e10c01		73.16	4.12										~		.0.335	
	_	16					53:55 d183		d183422b		73.42	3.32										2	023-07-17	16:53:	41
ŧ	1迹导出	17					3:55 d1f0		d1f0dc84		73.83	3.45													
		18	186047				53:55 d1f0		d1f01d92		37.67	-6.98	0.00	66	3 36.00	(FALSE	FALSE				2	023-07-17	16:532	41
		19					53:55 d1e1		d1e11d04		38.09	-7.28	0.00		7 31.00		FALSE	FALSE							
		20					53:55 03b3		03b35216		67.43	-6.52	0.00		\$ 36.70		FALSE	FALSE				2	023-07-17	16:532	42
		21					53:55 d182		d182db93		19.23	-6.46	0.00		38.50		FALSE	FALSE							
		22 23	186043 186042				53:55 d1e5		d1e5d503		59.89	-6.57	0.00		3 38.70		FALSE FALSE	FALSE			_	2	023-07-17	16:53:4	42
		23	186042				53:55 d1f0 53:55 d182		d1f04100 d182482e		51.02 93.22	-6.81	0.00		37.70 334.50		FALSE FALSE	FALSE							
		29	186040				53:55 d182		d1914900		74.21	2.10	0.00	90	5 54. 30		rnLog	FALSE				2	023-07-17	16:53:/	42
		26					53:54 d1 51		d1f05d15		73.88	4.30													
		27	186038				53:53 d1e1		d1e10c01		73.18	2.89										2	023-07-17	16:53:4	42
		28	186037				53:54 d183		d183422b		73.86	2.99													
		29	186036				53:54 d1f0		d1f0dc84		73.80	3.32										2	023-07-17	16:53:4	42
		30	186035				53:54 d1f0		d1f01d92		37.66	-7.09	0.00		3 36.00		FALSE	FALSE							
		31					53:54 d1e1		d1e11d04		38.10	-7.30	0.00		7 31.00		FALSE	FALSE			_	2	023-07-17	16:53:4	42
h	出界警告	32				16:	53:54 03b3	5216	03b35216		67.46	-6.55	0.00	64	4 36.70		FALSE	FALSE							
	持卡人员: d1f) E	Shee	t1										-						Þ	2	023-07-17	16:53:4	12
	围栏名称:区域	就語																III II II		+	100%				
					_		01914900		d1914900			未指定	/4	.43 2	2.11							2	023-07-17	16:53:4	10
_	111000				×		d1f05d15		d1f05d15			未指定	74	.01 4	4.13							2	023-07-17	16:53:4	40
U	出界警告 持卡人员: d1e		ı.				d1e10c01		d1e10c01			未指定	73	.44 2	2.43							2	023-07-17	16:53:4	41
	围栏名称:区域	1号					d183422b		d183422b			未指定	73	.72 3	3.03							2	023-07-17	16:53:	40



10 Other functions

10.1 Global language

The internationalization language function of the positioning system is an important feature that allows users to switch between Chinese and English to meet the language needs and preferences of different users.

Through the internationalization language function, users can choose to use Chinese or English as the interface and display language in the positioning system. This enables the positioning system to better adapt to the needs of global users and provide a more convenient user experience.

↓ 研迹®高精度实时定	位系统管理软件					_		_					* * 0	۲
Workbench	版 / Tag Management 版 Esc 跟批会用									Click to exit the ful	l screen mode			
System Config	Search Table													
Map Positioning	Serial Number	Blosso optor la	New establishes within the Mars Fater Alexandra Inter within										~	Q Search
Tag Management		Flease efficit le	Please enter letters or digits User Name Enter Chinese characters, letters, or digits Tag Type Please select											
Anchor Management	SOS	Please select	Please select v Online Status Please select v											C Reset
Alarm Record	± Export	± Import	1. Import										编辑未入网标签	C TI ®
Virtual Fence Historical trajectory	id 🗘	Serial 🗘	User N 🗘	User Color	Tag Type	X(m)	Y(m)	Z(m)	Battery 🗘	Temp.(°C)	Pressure(Pa)	SOS	Online Status	Operate
Trajectory export	1	d1e5d503	张三		Card(ProCarc	66.38	-8.65	0.00	20	16.2	0	Safe	Online	Edit
	2	cf804c96	李四		Safety Hat(P	-	-	-	-	-	+	Safe	Offline	Edit
	3	d1830811	王五		Digital Tag(P	37.58	-5.89	0.00	17	15.7	0	Safe	Online	Edit
	4	03d58096	赵六		Vehicle Tag(F	-	-	-	-	-	+	Safe	Offline	Edit
	5	03e3d18e	刘七		Alarm(ProTag	65.39	-8.84	2.66	17	13.7	101293	Safe	Online	Edit
	6	d1e18f18	防八		Unspecified	-	-	-	-	-		Safe	Offline	Edit
	8	d1e10826	昊九		Unspecified	-		-		-		Safe	Offline	Edit
	9	d1e5ce32	郑十		Unspecified	-	-	-	-	-	-	Safe	Offline	Edit
	10	d1e5ce32	James		Unspecified	-	-	-		-		Safe	Offline	Edit
	11	d1f05693	Isabella		Unspecified	-	-	-	-	-	-	Safe	Offline	Edit
	12	d1f05693	Benjamin		Unspecified	-		-		-	-	Safe	Offline	Edit
	13	d1829694	13		Unspecified	55.33	-8.36	0.00	20	18.7	0	Safe	Online	Edit
	14	d1829694	Elijah		Unspecified	55.33	-8.36	0.00	20	18.7	0	Safe	Online	Edit
	15	d182db93	嘧嘧嘧		Unspecified	92.95	-6.03	0.00	17	18.0	0	Safe	Online	Edit
	16	d182db93	Lucas		Unspecified	92.95	-6.03	0.00	17	18.0	0	Safe	Online	Edit
	17	d182463b	Amelia		Unspecified	21.15	-6.64	0.00	18	18.0	0	Safe	Online	Edit
0.1 build-512.1040 ==	18	d182463b	Alexander		Unspecified	21.15	-6.64	0.00	18	18.0	0	Safe	Online	Edit

10.2 Dark mode

The dark mode of the positioning system is a display mode of the user interface aimed at providing a more comfortable and low glare visual experience. Dark mode reduces brightness and contrast on the screen by changing the color theme of the user interface to a dark tone. This mode is suitable for use in dark environments or for users who are sensitive to brightness. The use of dark mode can reduce glare and eye fatigue, while also helping to save battery life (for devices with OLED or AMOLED screens)

⋛ 研迹®高精度实时定	位系统管理软件													• • •
Workbench	88 / Tag Manage	ment												
System Config	Search Table													
Map Positioning	Serial Number	Please enter le			lice	Name Enter		e lattere or diai		Tag Type				Q Search
										iog type Picase s				C Reset
Anchor Management					Online Status Please select									
Alarm Record	上 Export 上 Import の の の の の の の の の の の の の の の の の の の													
 Virtual Fence Historical trajectory 		Serial 🗘	User N 🗘	User Color	Tag Type	X(m)	Y(m)	Z(m)	Battery 🗘	Temp.(°C)	Pressure(Pa)		Online Status	Operate
Trajectory export		d1e5d503	张三		Card(ProCare	66.38	-8.65	0.00		16.2				
		cf804c96	李四		Safety Hat(P									
		d1830811	王五		Digital Tag(P	37.58	-5.89	0.00						
		03d58096	赵六		Vehicle Tag(F									
		03e3d18e	刘七		Alarm(ProTaj	65.39	-8.84	2.66			101293			
		d1e18f18	防八		Unspecified									
		d1e10826	昊九		Unspecified									
		d1e5ce32	X8 +		Unspecified									
		d1e5ce32	James		Unspecified									
		d1f05693	Isabella		Unspecified									
		d1f05693	Benjamin		Unspecified									
		d1829694			Unspecified	55.33	-8.36	0.00		18.7				
		d1829694	Elijah		Unspecified	55.33	-8.36	0.00		18.7				
		d182db93	嘧啶嘧		Unspecified	92.95	-6.03	0.00		18.0				
		d182db93	Lucas		Unspecified	92.95	-6.03	0.00		18.0				
		d182463b	Amelia		Unspecified	21.15	-6.64	0.00		18.0				
1.0.1 build-512.1040	18	d182463b	Alexander		Unspecified	21.15	-6.64	0.00	18	18.0	0	Safe	Online	Edit



11 Document Management Information Sheet

Subject	YANSENSE®High-Precision RTLS Management Software
Version	V2.0
Reference documents	
Creation time	2021/06/01
Founder	Yang, Huang
Latest release date	2023/01/01

Modifier	Date	Document change history
Yang, Huang	2021/06/01	V1.0 Version Release
Yang, Huang	2023/01/01	V2.0 Version Release